

Control Language for Distributed Clean

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The present Clean-CORBA interface supports the distributed computing using functional programming paradigms. Our aim is to express computations in the form of distributed process-networks. Nowadays it is very prevailing developing and testing parallel applications on PC clusters [1]. Therefore it became important to provide such distributed environments, which makes possible the investigation of typically distributed applications with client-programs written in any programming language.

In our environment [2],[3] Clean functional client-programs can be interconnected via CORBA, making possible the distribution of the processes and the asynchronous communication. Skeletal programming in the functional language Clean [4] extensively can use the CORBA server objects referenced by the parameterized clients. However for a controlled behaviour of the process-network a strategy description is needed. The distributed evaluation of functions and the communication between clients needs high-level process description and control mechanism [5]. In order to define such behaviour strategies a control language and its semantics is required.

The present paper would like to define high-level language elements for the coordination of the component functions in distributed environment. Parallel compositional strategies and primitives are defined with direct control over the process-network. These elements can be used by programmer for writing applications without knowing the details of the distributed environment.

References

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